SCHOOL AND SOME THE PAGE



PEROPT POCUMENTATION PAGE			area.	Form Approved OMB No. 0704-0188		
AD-A205 103		16. RESTRICTIVE	MARKINGS	गार	FILE COPY	
		3. DISTRIBUTION/AVAILABILITY OF REPORT  AFOSP/MI  Bolling AFE DC 20532-8448				
4. PERFORMING ORGANIZATION REPORT NUMBER(S)		5. MONITORING ORGANIZATION REPORT NUMBER(S)				
		AFOSR-TR. 89-0207				
6a. NAME OF PERFORMING ORGANIZATION	6b. OFFICE SYMBOL (If applicable)		ONITORING ORGA			
Yale University //EE	, ,,,,	AFOSR				
6c. ADDRESS (City, State, and ZIP Code)		7b. ADDRESS (City, State, and ZIP Code)				
	Building 410					
New Haven, Connecticut		Bolling, AFB DC 20332-6448				
8a. NAME OF FUNDING / SPONSORING ORGANIZATION	8b. OFFICE SYMBOL (If applicable)	9. PROCUREMENT INSTRUMENT IDENTIFICATION NUMBER				
AFOSR 8c. ADDRESS (City, State, and ZIP Code)	AFOSR -84-0242 10. SOURCE OF FUNDING NUMBERS					
		PROGRAM	PROJECT	TASK	WORK UNIT	
Building 410 Bolling, AFB DC 20332-6448		ELEMENT NO.	NO.	NO.	ACCESSION NO.	
11. TITLE (Include Security Classification)	61102F	2304	Al			
11. Title (include security destincation)						
ADAPTIVE CONTROL OF MULTIVARIABLE SYSTEMS						
12. PERSONAL AUTHOR(S) A. Stephen Morse						
13a. TYPE OF REPORT 13b. TIME CO FINAL FROMQ7/	4. DATE OF REPORT (Year, Month, Day) 15. PAGE COUNT 6 October 1988 4					
15. SUPPLEMENTARY NOTATION						
17. COSATI CODES 18. SUBJECT TERMS (Continue on reverse if necessary and identify by block number)						
FIELD GROUP SUB-GROUP						
	ł					
19. ABSTRACT (Continue on reverse if necessary and identify by block number)						
Research under this grant has focussed on adaptive control of mlutivariable systems.						
Seventeen papers were published under this grant, involving Adaptive Stabolization of						
Linear System with Unknown High-Frquency Gains" and "Indirect Adaptive Control of						
Processes Stisfving the Classical Assumptions of Direct Adaptive.						
Kyards, phingraphes, muticavele analysis. (kg) DELECTE						
1 5 FEL .989						
		•			Ce L	
E						
· · · · · · · · · · · · · · · · · · ·						
20. DISTRIBUTION/AVAILABILITY OF ABSTRACT		21. ABSTRACT SE	CURITY CLASSIFIC	ATION	5 5 7 7 <u>7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7</u>	
UNCLASSIFIED/UNLIMITED SAME AS F	RPT. DTIC USERS	Ollde	422			
22a. NAME OF RESPONSIBLE INDIVIDUAL Major James M. Crowley		22b. TELEPHONE ( (202) 767		22c. Of NN		
DD Form 1473, JUN 86	Previous editions are				FIGH OF THIS PAGE	

## ADAPTIVE CONTROL OF MULTIVARIABLE SYSTEMS

FINAL SCIENTIFIC REPORT

for the period

July 15, 1984 to July 14, 1988

Submitted to the

UNITED STATES AIR FORCE OFFICE OF SCIENTIFIC RESEARCH

under

AFOSR GRANT NO. 84-0242

A. Stephen Morse, Principal Investigator

October 6, 1988



Accession For					
NTIS	GRA&I	$\vec{z}$			
DTIC TAB					
Unannounced 🔲					
Justi cation					
Bv					
Distribution/					
Availability Codes					
	Avail an	d/or			
Dist	Special				
}	1				
	1. 1				
1 <i>H-I</i>					
<b>7</b>					

### I. INTRODUCTION

This is the final scientific report for AFOSR Grant No. 84-0242 covering the period July 15, 1984 to July 14, 1988. The work described below was undertaken in accordance with our previously submitted proposals.

#### II. COMPLETED WORK

## A. Research Reports and Papers

During the grant period, research leading to the following technical reports and papers was completed.

- [1] A. S. Morse, "New Directions in Parameter Adaptive Control,"

  Proc. 1984 IEEE Conf. on Decision and Control, Dec. 1984.
- [2] D. R. Mudgett and A. S. Morse, "Adaptive Stabilization of Linear Systems with Unknown High-Frequency Gains," <u>IEEE Trans. Auto.</u>

  <u>Control</u>, June 1985, also Proc. 1984 IEEE Conf. on Decision and Control, Dec. 1984.
- [3] D. R. Mudgett and A. S. Morse, "A Smooth Algorithm for Adaptive Stabilization of a Discrete Linear System with an Unknown High Frequency Gain," Proc. 1985 ACC, June 1985.
- [4] A. S. Morse, "A 4(n+1)-Dimensional Model Reference Adaptive Control for the Stabilization of Any Strictly Proper Minimum Phase Linear System with Relative Degree Not Exceeding Two and Dimension Not Exceeding n," Proc. 7th Int. Symp. on the Math. Theory of Networks and Systems, Stockholm, June 1985; also Automatica, January 1987.
- [5] D. R. Mudgett and A. S. Morse, "Adaptive Stabilization of a Discrete Linear System with an Unknown High-Frequency Gain," IEEE Trans. Auto. Control, Aug. 1985.
- [6] A. S. Morse, "A Three-Dimensional Universal Controller for the Adaptive Stabilization of Any Strictly Proper Minimum-Phase System with Relative Degree Not Exceeding Two," IEEE Trans. Auto. Control, December 1985.

- [7] C. I. Byrnes, U. Helmke and A. S. Morse, "Necessary Conditions in Adaptive Control," Proc. 7th Int. Symp. on the Math. Theory of Networks and Systems, Stockholm, June 1985.
- [8] A. S. Morse, "Simple Algorithms for Adaptive Stabilization," Proc. I.I.A.S.A. Conference on Modelling and Adaptive Control, Sopron, Hungary, July 1986.
- [9] A. S. Morse, "State Estimation Using Distributed Processing," Proc.

  IEEE Conf. on Decision and Control, Athens, December 1986.
- [10] D. R. Mudgett and A. S. Morse, "High-Order Parameter Adjustment Laws for Adaptive Stabilization," Proc. 1987 Johns Hopkins CISS Conf., Feb. 1987.
- [11] A. S. Morse, "High-Gain Feedback Algorithms for Adaptive Stabilization,"

  Proc. Fifth Yale Workshop on Applications of Adaptive Systems Theory,

  May 1987.
- [12] "Adaptive Stabilization by High Gain Feedback," Systems and Control Letters, to be submitted.
- [13] A. S. Morse, "Towards a Unified Theory of Parameter Adaptive Control Part I: Tunability," Proc. 1988 CDC, Austin, Texas; IEEE Trans. Auto.

  Control, to appear.
- [14] A. S. Morse, "Towards a Unified Theory of Parameter Adaptive Control Part II: Certainty Equivalence and Regulated Systems," IEEE Trans. Auto.
  Control, to appear.
- [15] A. S. Morse, "Indirect Adaptive Control of Processes Satisfying the Classical Assumptions of Direct Adaptive Control," Proc. 1988 ACC, Atlanta.
- [16] J. Huang and A. S. Morse, "A Computer Study of Adaptive Control Systems," Proc. 1988 ACC, Atlanta.
- [17] D. R. Mudgett, "Problems in Parameter Adaptive Control,"Doctoral Dissertation, Yale University, 1988.

## B. Presentations

During the grant period the following presentations were made at technical meetings.

- [1] A. S. Morse, "New Directions in Parameter Adaptive Control," IEEE Conf. on Decision and Control, Dec. 1984.
- [2] D. R. Mudgett and A. S. Morse, "Adaptive Stabilization of Linear Systems with Unknown High-Frequency Gains," IEEE Conf. on Decision and Control, Dec. 1984.
- [3] D. R. Mudgett and A. S. Morse, "A Smooth Algorithm for Adaptive Stabilization of a Discrete Linear System with an Unknown High Frequency Gain,"

  1985 ACC, June 1985.
- [4] A. S. Morse, "A 4(n+1)-Dimensional Model Reference Adaptive Control for the Stabilization of Any Strictly Proper Minimum Phase Linear System with Relative Degree Not Exceeding Two and Dimension Not Exceeding n,"

  7th Int. Symp. on the Math. Theory of Networks and Systems, Stockholm,
  June 1985.
- [5] C. I. Byrnes, U. Helmke and A. S. Morse, "Necessary Conditions in Adaptive Control," 7th Int. Symp. on the Math. Theory of Networks and Systems," Stockholm, June 1985.
- [6] A. S. Morse, "Simple Algorithms for Adaptive Stabilization," I.I.A.S.A.

  Conference on Modelling and Adaptive Control, Sopron, Hungary, July 1986.
- [7] A. S. Morse, "State Estimation Using Distributed Processing," IEEE Conf. on Decision and Control, Athens, December 1986.
- [8] D. R. Mudgett, "High-Order Parameter Adjustment Laws for Adaptive Stabilization," 1987 Johns Hopkins CISS Conf., Feb. 1987.
- [9] A. S. Morse, "High-Gain Feedback Algorithms for Adaptive Stabilization,"
  Fifth Yale Workshop on Applications of Adaptive Systems Theory, May 1987.
- [10] A. S. Morse, "Adaptive Stabilization by High-Gain Feedback," 1987 MTNS Conf., Phoenix, June 1987.

- [11] A. S. Morse, "Indirect Adaptive Control of Processes Satisfying the Classical Assumptions of Direct Adaptive Control," 1988 ACC, Atlanta.
- [12] J. Huang and A. S. Morse, "A Computer Study of Adaptive Control Systems,"
  1988 ACC, Atlanta.

# C. Miscellaneous

[1] <u>Doctoral Student</u>: One graduate student successfully completed his doctoral research under AFOSR support:

David Mudgett, "Problems in Parameter Adaptive Control, October 1988.